Bounding Blocking Time for EDF-DVS

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6th November 2002

We started with a simple task set consisting of two tasks and a single resource, for which both tasks contend. The task set we considered is (ϕ , p, e, d):

A (0, 8, 2, 8) and B (1, 5, 1, 5). Resource : $\mathbf X$

Resource Usage : A requires X for 1 time unit, from 0. B requires X for 1 time unit starting from 0.

Under normal EDF-PIP, the blocking term per resource per task, is calculated as follows:

 $\begin{array}{ll} b_{i,R\mathbf{j}} = \max_{1 \leq k \leq n} \left(\begin{array}{c} \theta_{\mathbf{k}} \end{array} \right) & \longrightarrow (1) \\ [\text{where } \theta_{\mathbf{k}} \text{ is the length of the critical section of every task using the resource } \mathbf{R}_{\mathbf{j}}] \\ \text{Now, the blocking term for task i is} \\ b_{\mathbf{i}} = \max_{1 \leq l \leq j} \left(\begin{array}{c} b_{i,R\mathbf{l}} \end{array} \right) & \longrightarrow (2) \\ \text{Here,} \\ b_{A} = 1 \text{ and } b_{\mathbf{B}} = 1. \end{array}$

This task set is schedulable (from the following schedulability test). $\sum_{k=1}^{n} e_k / \min(d_k, p_k) + b_i / \min(d_i, p_i) \le 1 \longrightarrow (3)$

Now, we consider EDF-PIP with DVS. We consider the static DVS mechanism.

We need to find the scaling factor α , such that $e_1/p_1 + e_2/p_2 \leq \alpha \longrightarrow (4)$

The lowest possible value of α is 0.45 in this case. Now, we scale the execution time of each task by this factor. The scaled values for the execution times are:

 $e_1 = 2 \ / \ \alpha = 2 \ / \ 0.45 = 4.44 \\ e_2 = 1 \ / \ \alpha = 1 \ / \ 0.45 = 2.22$

Similarly, the blocking times also need to be scaled. b_1 = 1 / α = 1 / 0.45 = 2.22 b₂ = 1 / α = 1 / 0.45 = 2.22

Once the scaling factor has been considered for both the execution and blocking times, the scheduling is exactly like normal EDF-PIP and is schedulable.

The blocking term for n tasks scheduled using EDF-PIP with Static-DVS is the same as the results obtained in equations (1) and (2) above. Care must be taken to ensure that the blocking times thus obtained are also scaled by $1 / \alpha$.

Note: In this particular example, we have used the lowest possible value for α obtained from equation (4). However, this may prove to be an over-optimistic value as blocking has not been considered in the calculation for α . In general, all task sets need not be schedulable if α is calculated in this way.

The correct way to estimate α is by using the following equation in place of equation (4):

 $\sum_{k=1}^{n} e_k / \min(d_k, p_k) + b_i / \min(d_i, p_i) \leq \alpha \longrightarrow (5)$

Since this is a static algorithm, it might be worthwhile to do the following: (a) Find the lowest possible value of α using equation (4)

(b) Scale the value of b_i using this value of α

(c) Perform the schedulability test according to equation (3)

(d) If this test fails, find α using equation (5) and proceed.

The value of α calculated in both cases would be significantly different.

Future course of work:

(a) Perform a formal analysis to verify the above results.

(b) Analyse for Cycle-Conserving DVS for EDF-PIP.

(c) Analyse for Look-Ahead DVS for EDF-PIP.

The work presented thus far had equal contributions by all three team members. We intend to continue working together for phase (a) mentioned above and then split the remaining work.